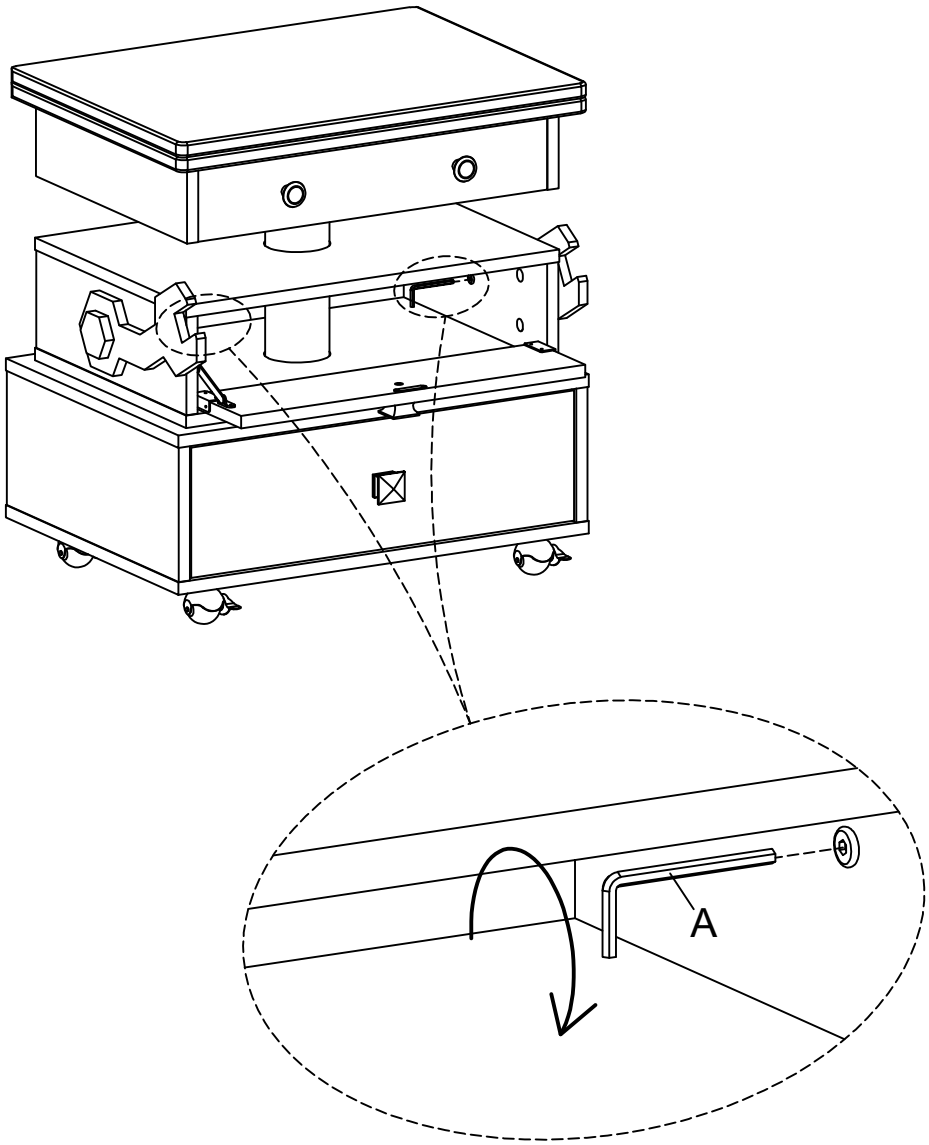
When the robot hand loosen ,you can use the part "A" tighten it



A		1