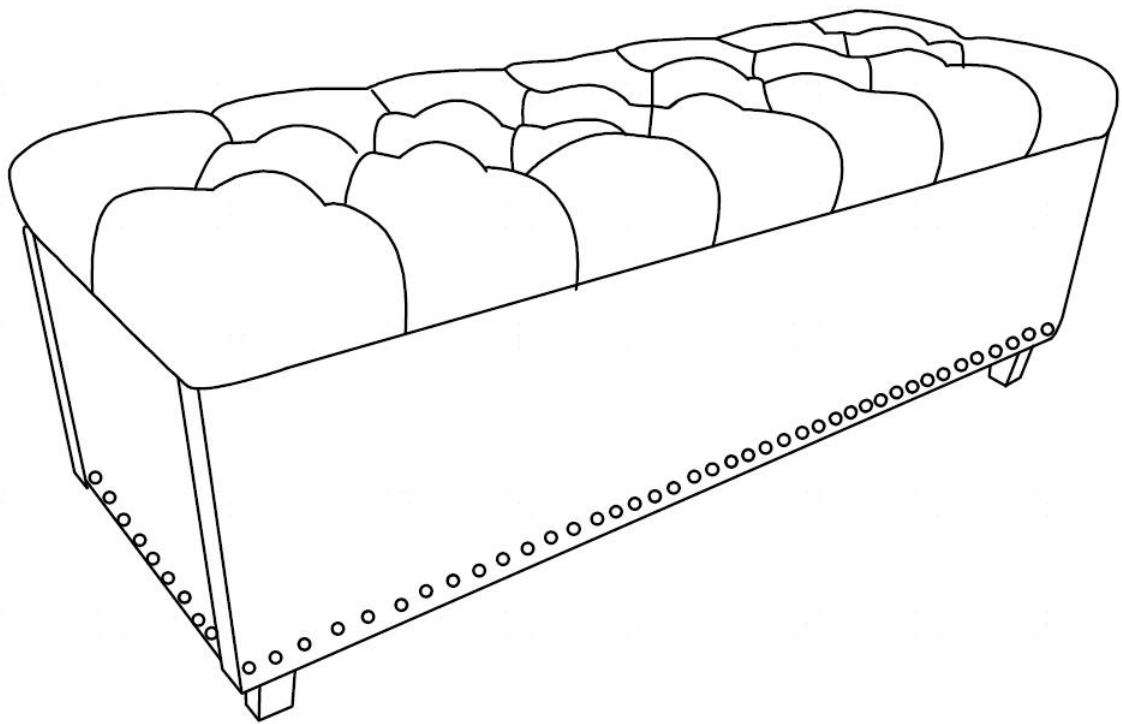
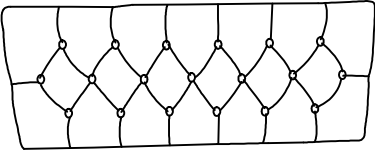
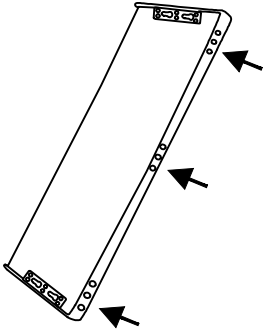
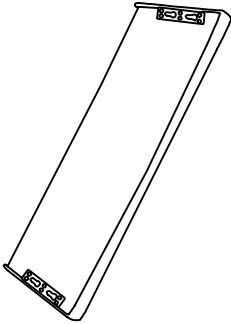
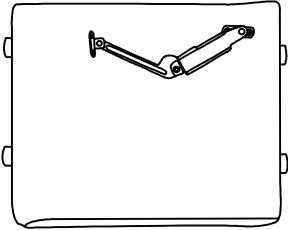
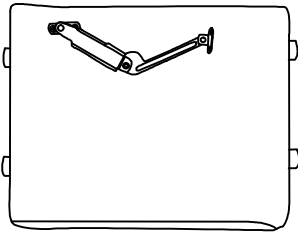
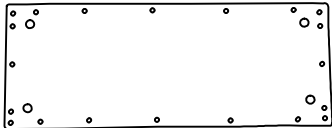
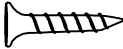
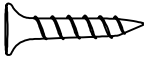


Ottoman Storage Benches



PART LIST

BOX -

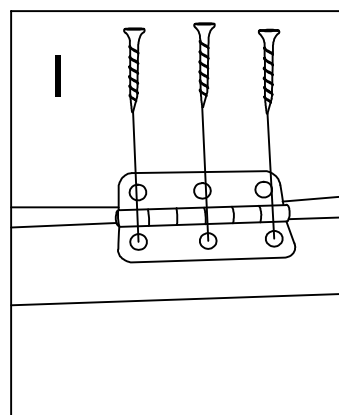
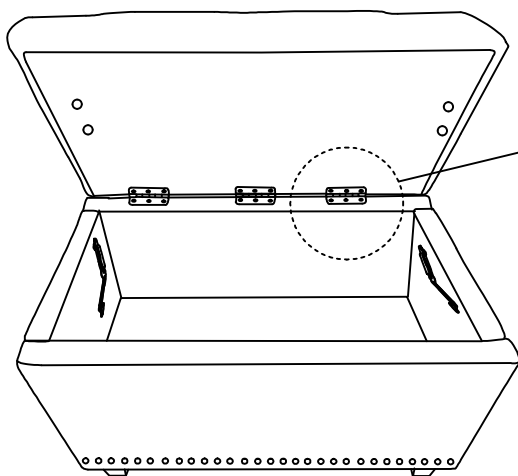
A*1 	B*1  Screw hole position	C*1 
D*1 	E*1 	F*1 
G*4 	H*4 	I*14  4 *25mm
J*20  4 *35mm	K*1 	

STEP

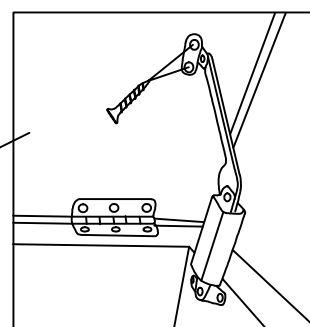
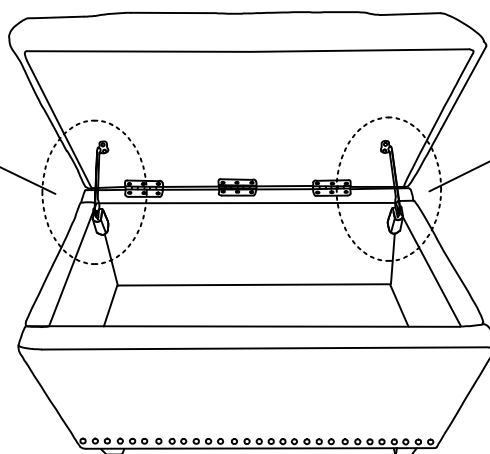
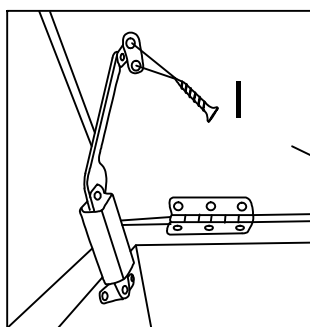
A schematic diagram of a hexapod robot, which is a six-legged robot. The robot has a rectangular body with a row of small circles along the bottom edge, representing legs. Four cameras are mounted on the robot, one on each of the four long sides. Each camera is labeled with a letter: 'G' for the top-left, 'H' for the top-right, 'I' for the bottom-left, and 'J' for the bottom-right. Each camera is shown with a lens and a viewing frustum. Arrows indicate the rotation of each camera around its mounting point.

STEP

4



5



6

